Q.P. Code: 16EE216

KIO

Reg. No:

SIDDHARTH INSTITUTE OF ENGINEERING & TECHNOLOGY:: PUTTUR (AUTONOMOUS)

B.Tech III Year I Semester Supplementary Examinations Feb-2021 LINEAR CONTROL SYSTEMS

(Electrical and Electronics Engineering)

Time: 3 hours

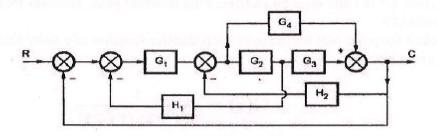
Max. Marks: 60

(Answer all Five Units $5 \times 12 = 60$ Marks)

UNIT-I

a Using Block diagram reduction technique find the Transfer Function of the system

8M



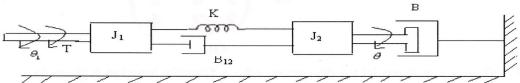
b Distinguish between Block diagram Reduction Technique and Signal Flow Graph?

4M

a Derive the transfer function for synchro with neat diagram?

4M

b Write the differential equations governing the mechanical rotational system shown **8M** in the figure and find transfer function.



UNIT-II

3 List out the time domain specifications and derive the expressions for Rise time, Peak time and Peak overshoot.

12M

OR

For servo mechanisms with open loop transfer function given below what type of input 12M signal give rise to a constant steady state error and calculate their values.

$$G(s)H(s)=\frac{10}{S^2(S+1)(S+2)}$$

UNIT-II

a With the help of Routh"s stability criterion find the stability of the following systems represented by the characteristic equations:

6M

6M

 $s^6 + 2s^5 + 8s^4 + 12s^3 + 20s^2 + 16s + 16 = 0.$

b Using Routh's criteria determine the stability for open loop transfer function has poles at s = 0, s = -1, s = -3 and zeros at s = -5, Gain k of forward path is "10".

OR

6 Sketch the root locus of the system whose open loop transfer function is

12M

G(s) H(s) =
$$\frac{K}{S(S+4)(S^2+4S+20)}$$

7 a Band width is directly proportional to ω_n Justify.

4M

b Draw the Bode plot for the system having the following transfer function

8M

$$G(s) = \frac{15(S+5)}{S(S^2 + 16S + 100)}$$
OR

8 a Given $\xi = 0.7$ and $\omega_n = 10$ rad/sec. Find resonant peak, resonant frequency and bandwidth.

6M

b Sketch the polar plot for the open loop transfer function of a unity feedback system is given by

6**M**

$$G(s) = \frac{1}{s(1+s)(1+2s)}$$

Determine Phase margin and gain margin.

UNIT-V

9 a State the properties of state transition matrix

6M

b Diagonalize the following system matrix

6M

$$A = \begin{pmatrix} 0 & 6 & -5 \\ 1 & 0 & 2 \\ 3 & 2 & 4 \end{pmatrix}$$

OR

10 Obtain a state model for the system whose Transfer function is given by

12M

$$\frac{Y(s)}{U(s)} = \frac{(7S^2 + 12S + 8)}{(S^3 + 6S^2 + 11S + 9)}$$

*** END ***